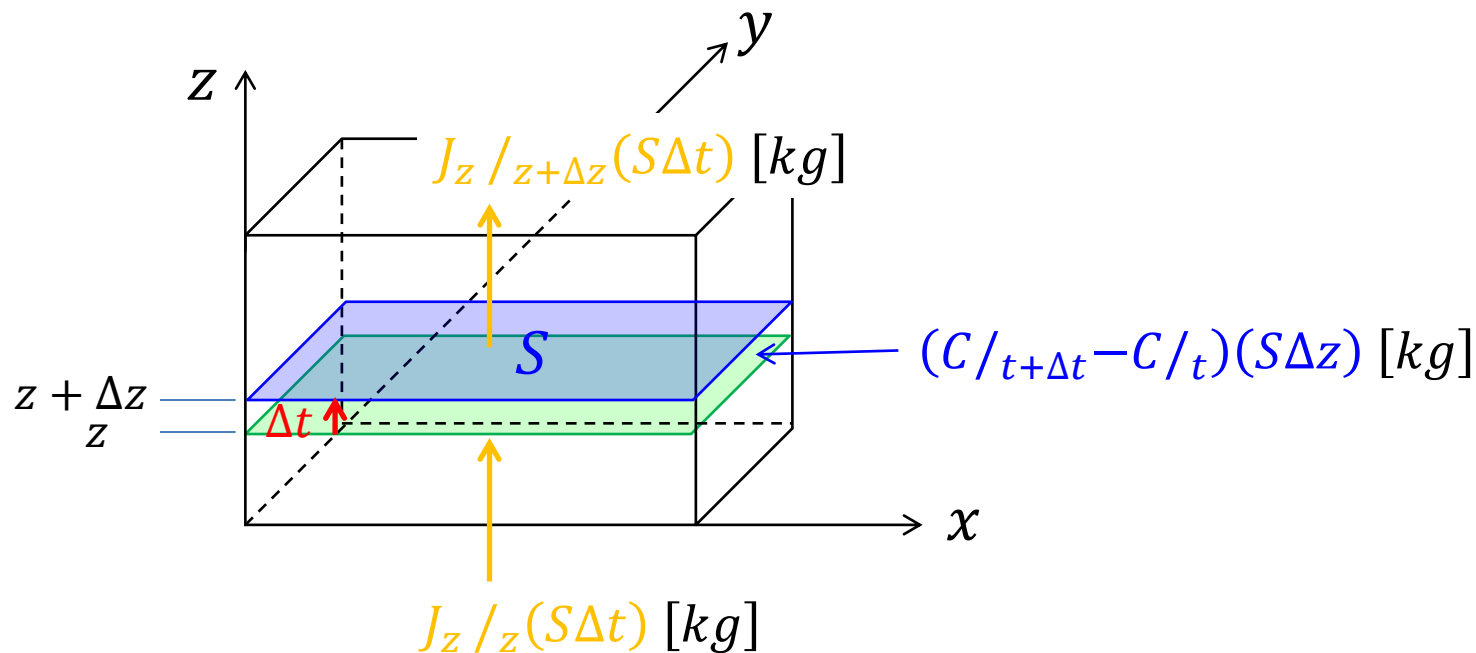




$$J_z / z (S\Delta t) - (C / t + \Delta t - C / t) (S\Delta z) - 0 = J_z / z + \Delta z (S\Delta t)$$

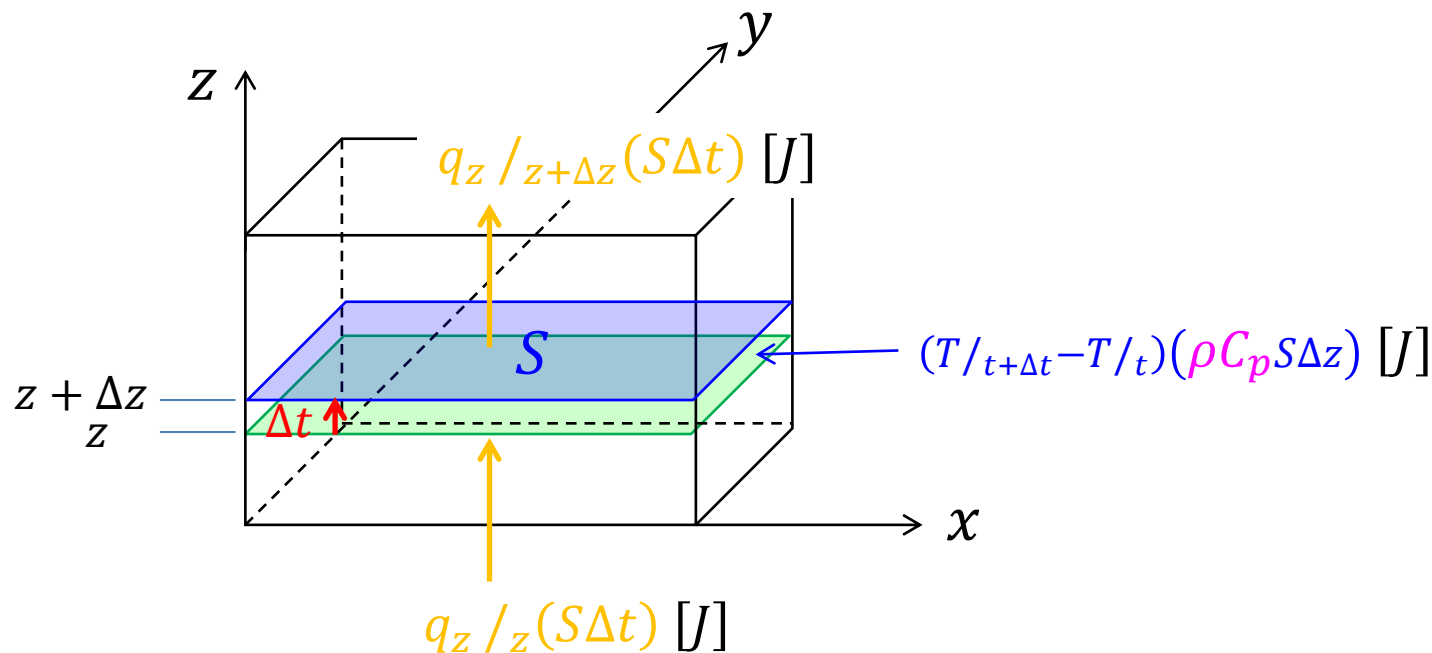
インプット
溜まり
消失
アウトプット

$$-\frac{C / t + \Delta t - C / t}{\Delta t} = \frac{J_z / z + \Delta z - J_z / z}{\Delta z}$$

$$-\frac{\partial C}{\partial t} = \frac{\partial J_z}{\partial z}$$

$$J_z = -D \frac{\partial C}{\partial z} \text{を代入して} \quad -\frac{\partial C}{\partial t} = \frac{\partial \left(-D \frac{\partial C}{\partial z} \right)}{\partial z}$$

$$\frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial z^2}$$



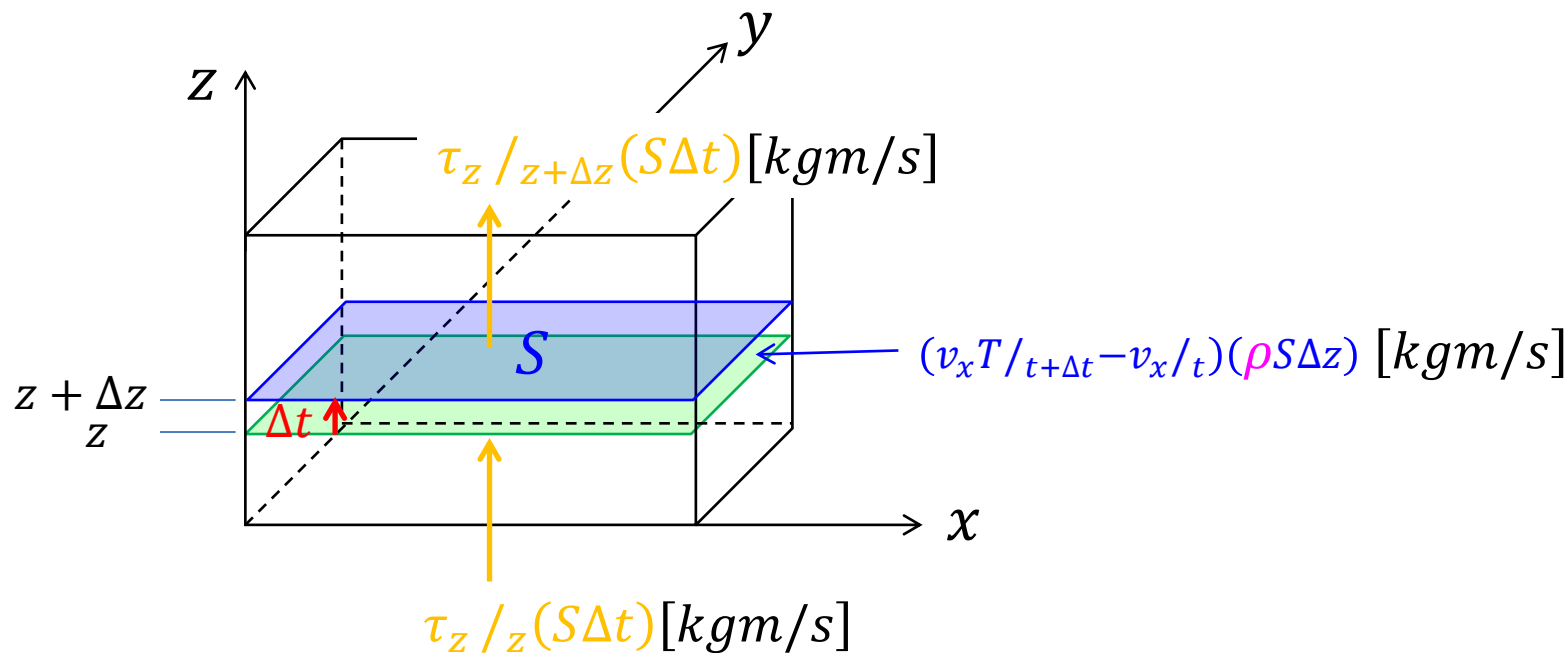
$$q_z / z (S\Delta t) - (T / t + \Delta t - T / t) (\rho C_p S\Delta z) - 0 = q_z / z + \Delta z (S\Delta t)$$

インプット
溜まり
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アウトプット

$$-\rho C_p \frac{T / t + \Delta t - T / t}{\Delta t} = \frac{q_z / z + \Delta z - q_z / z}{\Delta z}$$

$$-\rho C_p \frac{\partial T}{\partial t} = \frac{\partial q_z}{\partial z}$$

$$q_z = -k \frac{\partial T}{\partial z} \text{を代入して} \quad -\rho C_p \frac{\partial T}{\partial t} = \frac{\partial \left(-k \frac{\partial T}{\partial z} \right)}{\partial z} \quad \frac{\partial T}{\partial t} = \left(\frac{k}{\rho C_p} \right) \frac{\partial^2 T}{\partial z^2}$$



$$\tau_z / z (S \Delta t) - (v_x / t + \Delta t - v_x / t) (\rho S \Delta z) - 0 = \tau_z / z + \Delta z (S \Delta t)$$

インプット
溜まり
消失
アウトプット

$$-\rho \frac{v_x / t + \Delta t - v_x / t}{\Delta t} = \frac{\tau_z / z + \Delta z - \tau_z / z}{\Delta z}$$

$$-\rho \frac{\partial v_x}{\partial t} = \frac{\partial \tau_z}{\partial z}$$

$$\tau_z = -\mu \frac{\partial v_x}{\partial z} \text{を代入して} \quad -\rho \frac{\partial v_x}{\partial t} = \frac{\partial \left(-\mu \frac{\partial v_x}{\partial z} \right)}{\partial z} \quad \frac{\partial v_x}{\partial t} = \left(\frac{\mu}{\rho} \right) \frac{\partial^2 v_x}{\partial z^2}$$

$$\frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial z^2}$$

$$\frac{\partial T}{\partial t} = \left(\frac{k}{\rho C_p} \right) \frac{\partial^2 T}{\partial z^2}$$

$$\frac{\partial v_x}{\partial t} = \left(\frac{\mu}{\rho} \right) \frac{\partial^2 v_x}{\partial z^2}$$

$$\alpha = \frac{k}{\rho C_p}$$

$$v = \frac{\mu}{\rho}$$

$$\frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial z^2}$$

$$\frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial z^2}$$

$$\frac{\partial v_x}{\partial t} = v \frac{\partial^2 v_x}{\partial z^2}$$

$[m^2/s]$



$$\frac{\partial \blacksquare}{\partial t} = v \frac{\partial^2 \blacksquare}{\partial z^2}$$

放物線型

$$\frac{\partial f}{\partial t} = 2 \text{ を積分すると } f(t) = 2t + C_1$$

例えば、 $t = 0$ のとき $f(0) = 3$ であれば ← 境界条件1つ

$$C_1 = 3 \text{ となり、 } f(t) = 2t + 3$$

$$\frac{\partial^2 f}{\partial z^2} = 2 \text{ を積分すると } f(z) = z^2 + C_1 z + C_2$$

例えば、 $z = 0$ のとき $f(0) = 2$ 、

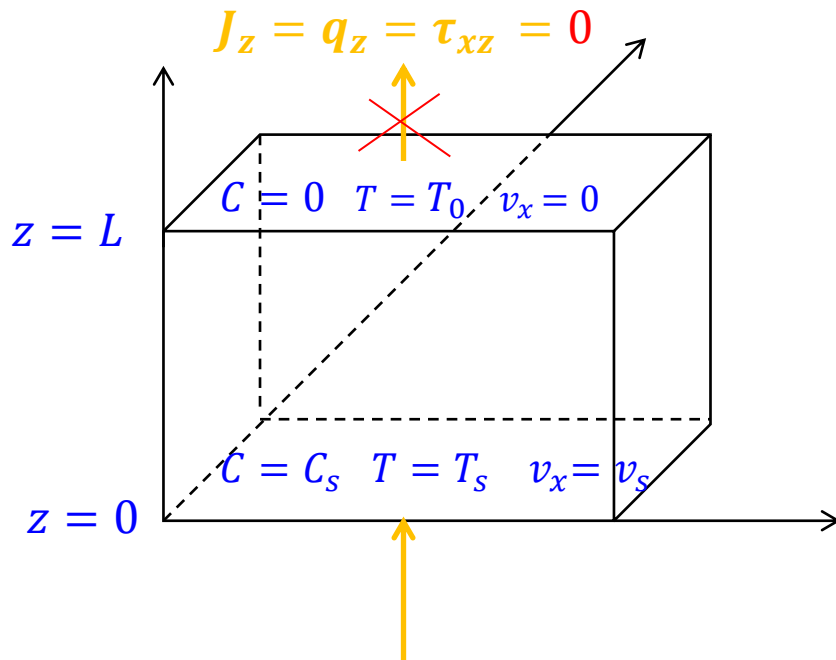
$z = 0$ のとき $\frac{\partial f}{\partial z} = 4$ であれば

← 境界条件2つ

$$f(z) = z^2 + 4z + 2$$

$$\frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial z^2}$$

$$\begin{array}{llll} t = 0 & C = 0 & z = L & J_z = 0 \\ z = 0 & C = C_s & & \downarrow \\ & & z = L & -D \frac{\partial C}{\partial z} = 0 \\ & & & \downarrow \\ z = L & C = 0 & z = L & \frac{\partial C}{\partial z} = 0 \end{array}$$



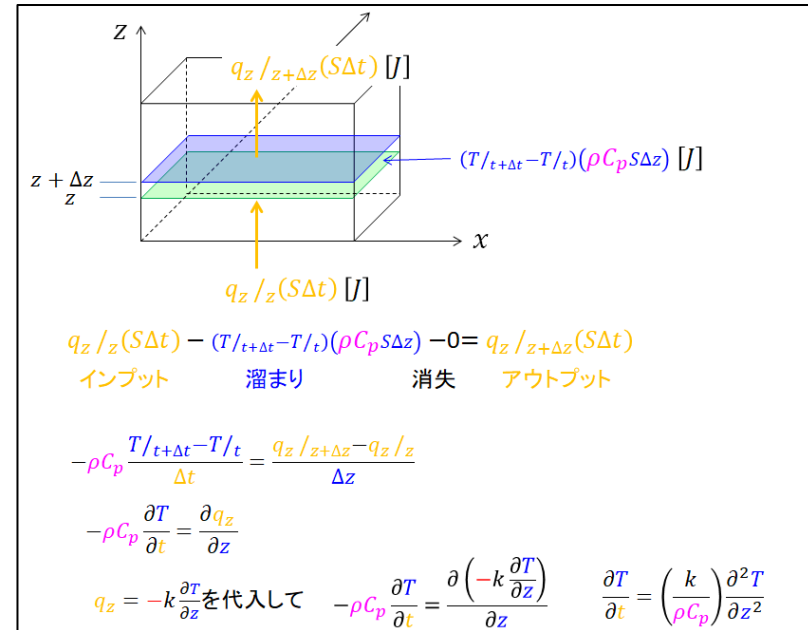
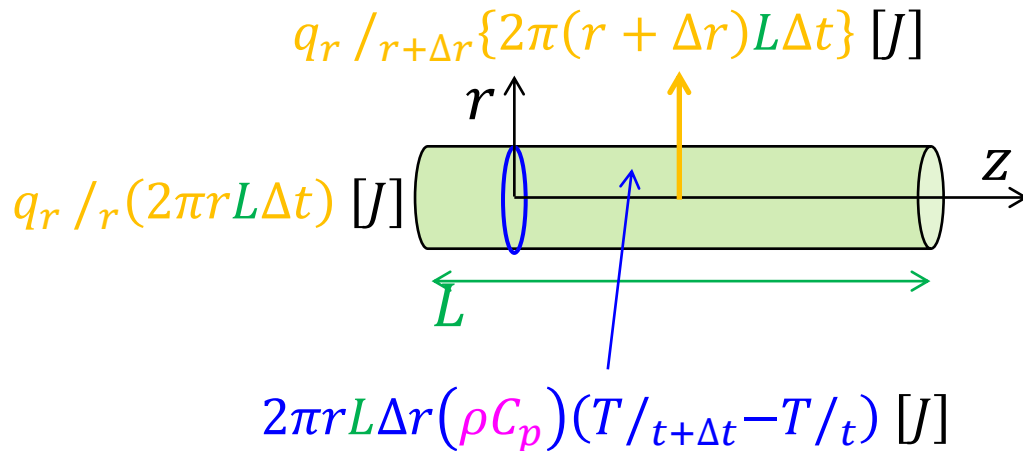
$$\frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial z^2}$$

$$\begin{array}{llll} t = 0 & T = T_0 & z = L & q_z = 0 \\ z = 0 & T = T_s & & \downarrow \\ & & z = L & -k \frac{\partial T}{\partial z} = 0 \\ & & & \downarrow \\ z = L & T = T_0 & z = L & \frac{\partial T}{\partial z} = 0 \end{array}$$

$$\frac{\partial v_x}{\partial t} = \nu \frac{\partial^2 v_x}{\partial z^2}$$

$$\begin{array}{llll} t = 0 & v_x = 0 & z = L & \tau_{xz} = 0 \\ z = 0 & v_x = v_s & & \downarrow \\ & & z = L & -\mu \frac{\partial v_x}{\partial z} = 0 \\ & & & \downarrow \\ z = L & v_x = 0 & z = L & \frac{\partial v_x}{\partial z} = 0 \end{array}$$

円筒状のきゅうりを冷蔵庫で冷やす



$$q_r / r (2\pi r L \Delta t) - 2\pi r L \Delta r (\rho C_p) (T/t + \Delta t - T/t) - 0 = q_r / r + \Delta r \{ 2\pi(r + \Delta r)L\Delta t \}$$

インプット 溜まり 消失 アウトプット

$$-\rho C_p \frac{T/t + \Delta t - T/t}{\Delta t} = \frac{q_r / r + \Delta r - q_r / r}{\Delta r} + \frac{1}{r} q_r / r + \Delta r$$

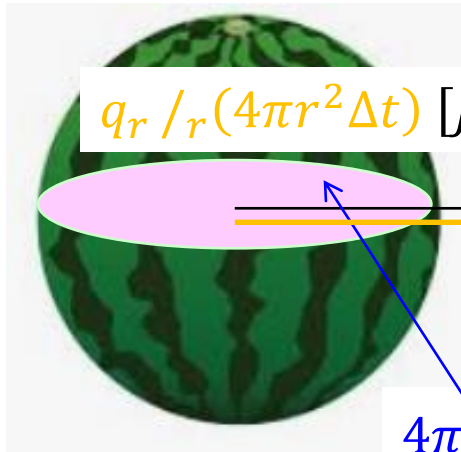
$$-\rho C_p \frac{\partial T}{\partial t} = \frac{\partial q_r}{\partial r} + \frac{1}{r} q_r$$

$$q_r = -k \frac{\partial T}{\partial r} \text{ を代入して } -\rho C_p \frac{\partial T}{\partial t} = \frac{\partial \left(-k \frac{\partial T}{\partial r} \right)}{\partial r} + \frac{1}{r} \left(-k \frac{\partial T}{\partial r} \right)$$

r の増加に伴う補正として $\frac{1}{r}$ を掛ける

$$\frac{\partial T}{\partial t} = \alpha \left(\frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r} \right)$$

球状のスイカを冷蔵庫で冷やす

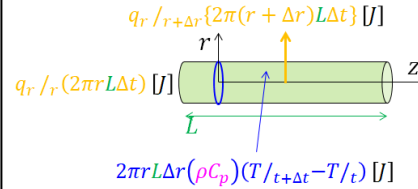


$$q_r / r (4\pi r^2 \Delta t) [J]$$

$$q_r / r + \Delta r \{4\pi (r + \Delta r)^2 \Delta t\} [J]$$

$$4\pi r^2 \Delta r (\rho C_p) (T / t + \Delta t - T / t) [J]$$

円筒状のきゅうりを冷蔵庫で冷やす



$$q_r / r + \Delta r \{2\pi (r + \Delta r) L \Delta t\} [J]$$

$$q_r / r (2\pi r L \Delta t) [J]$$

$$2\pi r L \Delta r (\rho C_p) (T / t + \Delta t - T / t) [J]$$

$$q_r / r (2\pi r L \Delta t) - 2\pi r L \Delta r (\rho C_p) (T / t + \Delta t - T / t) - 0 = q_r / r + \Delta r \{2\pi (r + \Delta r) L \Delta t\}$$

インプット 溜まり 消失 アウトプット

$$-\rho C_p \frac{T / t + \Delta t - T / t}{\Delta t} = \frac{q_r / r + \Delta r - q_r / r}{\Delta r} + \frac{1}{r} q_r / r + \Delta r$$

$$-\rho C_p \frac{\partial T}{\partial t} = \frac{\partial q_r}{\partial r} + \frac{1}{r} q_r$$

$$q_r = -k \frac{\partial T}{\partial r} \text{を代入して} \quad -\rho C_p \frac{\partial T}{\partial t} = \frac{\partial}{\partial r} \left(-k \frac{\partial T}{\partial r} \right) + \left(\frac{1}{r} \left(-k \frac{\partial T}{\partial r} \right) \right) \quad \frac{\partial T}{\partial t} = \alpha \left(\frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r} \right)$$

$$q_r / r (4\pi r^2 \Delta t) - 4\pi r^2 \Delta r (\rho C_p) (T / t + \Delta t - T / t) - 0 = q_r / r + \Delta r \{4\pi (r + \Delta r)^2 \Delta t\}$$

インプット 溜まり 消失 アウトプット

$$-\rho C_p \frac{T / t + \Delta t - T / t}{\Delta t} = \frac{q_r / r + \Delta r - q_r / r}{\Delta r} + \left(\frac{2}{r} + \frac{\Delta r}{r^2} \right) q_r / r + \Delta r$$

$$-\rho C_p \frac{\partial T}{\partial t} = \frac{\partial q_r}{\partial r} + \frac{2}{r} q_r$$

$$q_r = -k \frac{\partial T}{\partial r} \text{を代入して} \quad -\rho C_p \frac{\partial T}{\partial t} = \frac{\partial}{\partial r} \left(-k \frac{\partial T}{\partial r} \right) + \frac{2}{r} \left(-k \frac{\partial T}{\partial r} \right) \quad \frac{\partial T}{\partial t} = \alpha \left(\frac{\partial^2 T}{\partial r^2} + \frac{2}{r} \frac{\partial T}{\partial r} \right)$$

円筒よりさらに拡がり大